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TRACK/TRAIN DYNAMICS
TEST PROCEDURE
TRANSFER FUNCTION TEST

Contract NAS8-29882

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## FOREWORD

This document is submitted in accordance with the requirements of NASA Contract NAS8-29882.

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#### 1.0 SCOPE

This procedure provides the necessary information and detailed operations required to conduct the transfer function vibration test on an 80 ton open hopper freight car.

- 1.1 Objective The objective of the transfer function test is to obtain data for the validation of the freight car nonlinear elastic model.
- 1.2 <u>Summary</u> The test configuration, handling, test facilities, test operations, and data acquisition/reduction activities necessary to meet the conditions of the test requirements document (TS-005-TF) are delineated herein.

#### 2.0 TEST CONFIGURATION

The test article will be setup as illustrated in Figure 7.1.

## 3.0 SUPPORT REQUIREMENTS

- 3.1 <u>Handling Equipment</u> The support equipment necessary to move the freight car, shakers, and coal is listed in Table 8.1.
- 3.2 <u>Test Equipment</u> The support equipment necessary to conduct the test is listed in Table 8.2.

#### 3.3 Reference Documents -

- 3.3.1 P74-48338-1, "Track-Train Dynamics Analysis and Test
  Program," Update
- 3.3.2 TS-005-TF, "Track/Train Dynamics Test Requirements

  Document, Transfer Function Test"
- 3.3.3 LAB 1007302, "Track-Dynamic Analysis GVS and Transfer Function Test"

- 3.3.4 LAB 0212205, Sinewave Vibration Control Standard
  Operating Procedure
- 3.3.5 1923-5017, Time/Data Sinusoidal Vibration Control
  Manual

## 3.4 Facility Requirements -

- 3.4.1 115 VAC, 60 Hz, 1 Ø
- 3.4.2 440 VAC, 60 Hz, 3 Ø
- 3.4.3 Hydraulic Power Supply

#### 4.0 SPECIAL CONSIDERATIONS

- 4.1 <u>Cautions and Warnings</u> The description appearing within a <u>CAUTION</u> or <u>WARNING</u> precedes the information that it is intended to emphasize. A <u>CAUTION</u> is used to prevent personnel from damaging equipment. A <u>WARNING</u> is used to prevent test personnel from endangering their safety or that of others. Each step of this procedure shall be read completely before proceeding with the action.
- 4.2 <u>Test Discrepancies</u> A test discrepancy shall be logged and reported when test performance and/or results are affected.
- 4.3 <u>Safety</u> MMC supervision are directly responsible for the safety of all personnel, safe working conditions and the implementation of all safety requirements applicable to this procedure.
  - 4.3.1 All test team members are responsible for adhering to normal safety standards and procedures. They are also responsible for advising of any unsafe acts or conditions observed during preparation for or during conduct of this procedure.

- 4.3.2 Personnel safety will be notified 24 hours prior to the official test start date. This test is classified as having non-destructive potential.
- 4.4 <u>Procedure Changes</u> All changes to this procedure will be documented and added to a post-test procedure update.

## 4.5 <u>Test Personnel</u>

Code	<u>Description</u>	<u>Quantity</u>
TD	Technical Director	1
TE	Test Engineer	1
MT	Mechanical Technician	1
ET	Electronic Technician	1
SF	Safety	1

- 4.6 <u>Test Log</u> A test log shall be maintained during the test and shall contain information for a complete historical chronological description of test activities.
  - 4.6.1 Instrumentation setup sheets shall be maintained and form part of the test log.
- 4.7 <u>Test Data</u> Provision shall be made to retain all test data for a period of 18 months after the test completion.
- 4.8 <u>Test Control Board</u> A test control board (TCB) shall periodically monitor test activities and shall consist of the following personnel:

<u>Name</u>	<u>Title</u>	Function	
G. Morosow	Project Manager (MMC)	Chairman	
P. Abbott	Technical Director (MMC)	Member	
J. Macpherson	Technical Representative (NASA/MSFC)	Member	

5.0  5.1  Preparations  Preparations  5.1.1  MT  Solution the freight car in the facility per drawing LAB 1007302.  Install hydraulic power supply near actuator test positions.  Install aft truck support, forward slide plates and load cell/spacer assemblies per LAB 1007302. Locate load cells under wheel 1 and 2 per Figure 7.3 and measure static load.  Install actuator support fixture per LAB 1007302.  Install actuators for (Y) direction tests per Figure 7.1.  Install instrumentation in the locations identified by Figures 7.2, 7.3 and Table 8.3. Record data in Table 8.4.  Setup actuator system and data acquisition/reduction equipment as shown in Figure 7.1.  Connect and route all interconnecting cables and plumbing per Figure 7.4.  Verify data acquisition equipment operation, tap check transducers, record full scale calibrations and log information in Table 8.4.	RKS
5.1.1 MT — Position the freight car in the facility per drawing LAB 1007302.  5.1.2 MT — Install hydraulic power supply near actuator test positions.  5.1.3 MT,ET — Install aft truck support, forward slide plates and load cell/spacer assemblies per LAB 1007302. Locate load cells under wheel 1 and 2 per Figure 7.3 and measure static load.  5.1.4 MT — Install actuator support fixture per LAB 1007302.  5.1.5 MT — Install actuators for (Y) direction tests per Figure 7.1.  5.1.6 ET — Install instrumentation in the locations identified by Figures 7.2, 7.3 and Table 8.3. Record data in Table 8.4.  5.1.7 ET/MT — Setup actuator system and data acquisition/reduction equipment as shown in Figure 7.1.  5.1.8 ET/MT — Connect and route all interconnecting cables and plumbing per Figure 7.4.  Verify data acquisition equipment operation, tap check transducers, record full scale calibrations and	
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cables and plumbing per Figure 7.4.  Verify data acquisition equipment operation, tap check transducers, record full scale calibrations and	
operation, tap check transducers, record full scale calibrations and	
5.1.10 ET Load sine control program in computer and verify operation per Time/Data manual.	
5.2 <u>Detailed Operations</u>	•
Perform a 2000 1b-pk sinewave sweep from 0.5 to 50 Hz controlling FL1 per LAB 0212205 and record all data channels.	ol Abort <u>+</u> 3dB

STEP NO.	RESPONS- IBILITY	ск	ACTION	REMARKS
5.2.2	ET		Load transfer function program and plot selected data per TD.	
5.2.3	TE/et al		Load sine control program, perform a 5000 lb-pk sine sweep from 0.5 to 50 Hz controlling FL1 per LAB 0212205 and record data.	Limit Actuator Displ. to <u>+</u> 2" D.A.
5.2.4	ET		Load transfer function program and plot selected data per TD.	
5.2.5	TE/et al		Load sine control program, perform a 10,000 1b-pk sine sweep from 0.5 to 50 Hz controlling FLl per LAB 0212205 and record data. Also, take movies of car/truck motion.	
5.2.6	TE		Load transfer function program and plot selected data per TD.	
5.2.7	TE/et al		Load sine program and repeat steps 5.2.1 through 5.2.6 with the actuators 180° out of phase.	
5.2.8	MT		Photograph test setup and actuator/ transducer locations.	·
5.2.9	MΊ		Install actuators for (X) direction tests and vertical load cells per Figures 7.1 and 7.3.	
5.2.10	TE/et al		Repeat step 5.2.7, except control measurement FL3.	
5.2.11	мт		Photograph new actuator locations	,
5.2.12	MT		Install a single actuator for (Z) direction tests per Figure 7.1.	
5.2.13	TE/et al		Load sine program and perform steps 5.2.1 through 5.2.6, except control measurement FV1.	
5.2.14	MI		Photograph actuator location.	
5.2.15	ET		Complete data reduction per TD.	
5.3			Post-Test Review	
5.3.1	TCB		Perform post-test review to verify test objectives & terminate test.	

STEP NO.	RESPONS- IBILITY	CK	ACTION	REMARKS
5.4 5.4.1	MT/ET		Post-Test Disassembly  Remove all instrumentation, actuators and fixturing.	
5.4.2	MT		Unload coal	
5.4.3	TE	, -	Prepare data package containing logs, setup sheets, photographs and data.	
				6

#### 6.0 ABBREVIATION AND ACRONYMS

Calib. Calibration

Cap. Capacity

CDC Control Data Corporation

Ch. Channel

Ck. Check

CO Coincidence Component

ET Electronic Technician

FS Full Scale

Meas. Measurement

Mfg. Manufacturer

MMC Martin Marietta Corporation

MSFC Marshall Space Flight Center

MT Mechanical Technician

NASA National Aeronautics and Space Administration

No. Number

O-Graph Oscillograph

Osc. Oscillator

Qty. Quantity

QUAD Quadrature Component

Sens. Sensitivity

SF Safety

SW Switch

TCB Test Control Board

TD Technical Director

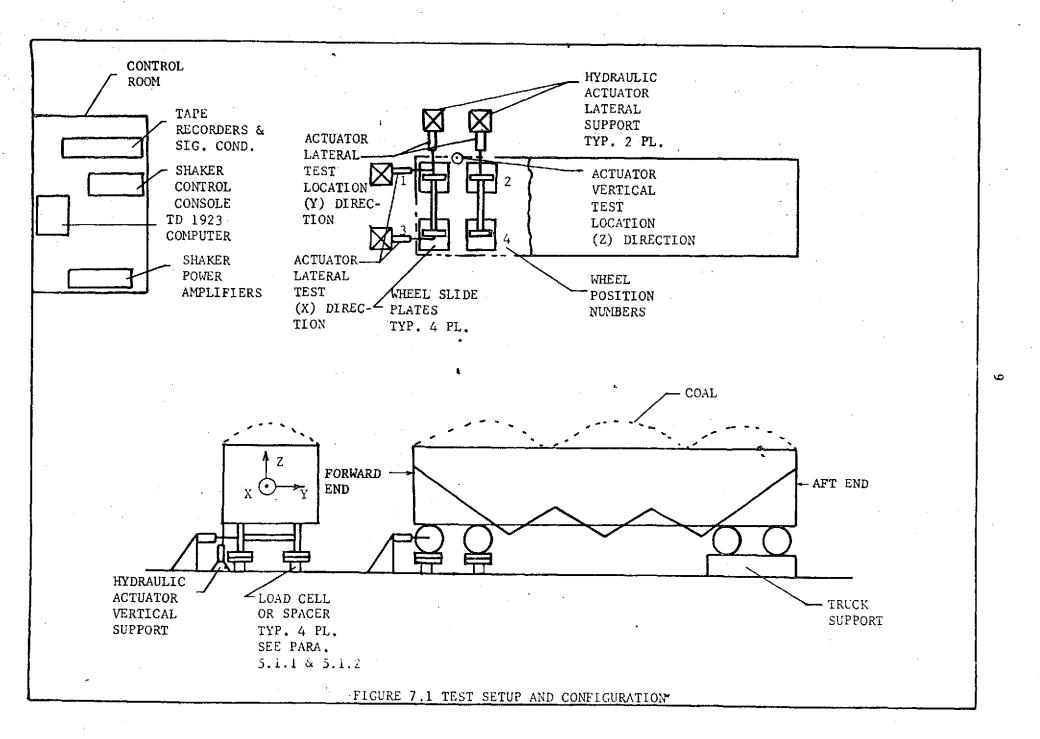
TE Test Engineer

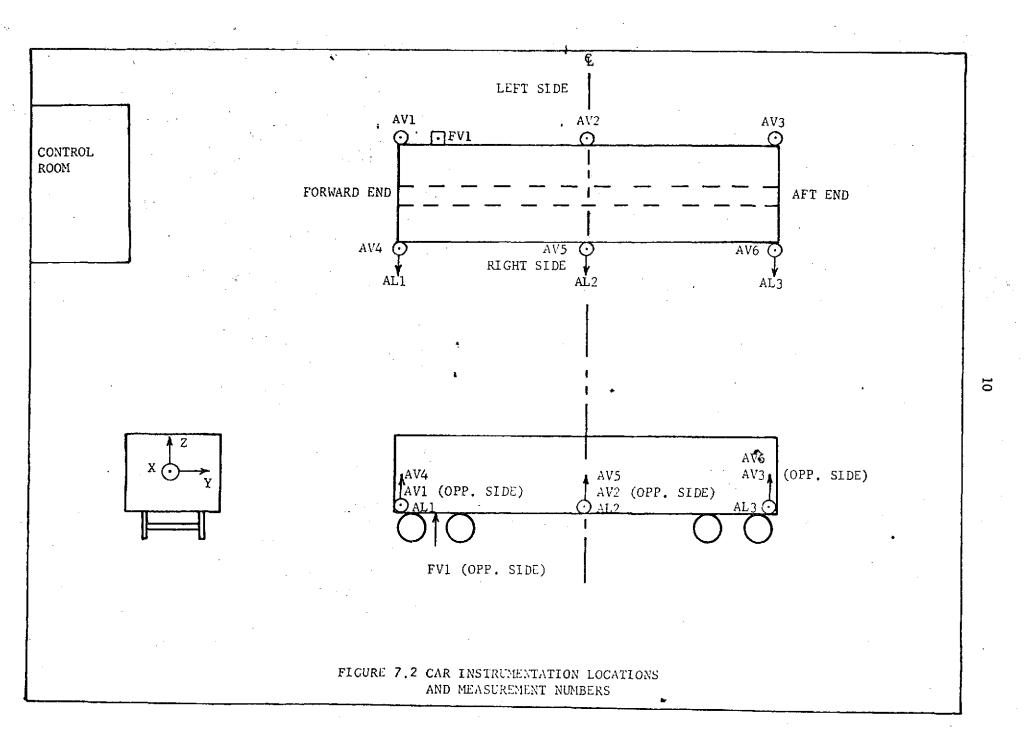
TTY Teletype Terminal

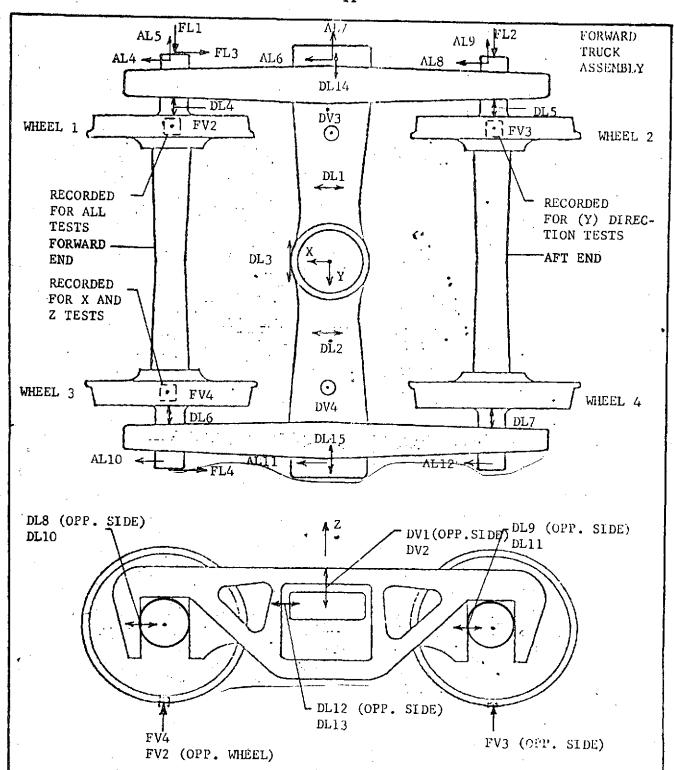
Typ. Typical

U-D Unholtz-Dickie Corporation

XDCR Transducer







NOTES: DL1,2&3 ARE RELATIVE DISPL. OF BOLSTER WRT CAR, ALSO DV3 & DV4
DL4 THROUGH DL11 ARE RELATIVE DISPL. OF SIDE FRAMES WRT AXLE
DV1, DV2, DL12 & DL13 ARE RELATIVE DISPL. OF BOLSTER WRT SIDE FRAMES,
ALSO DL14 & DL15

FIGURE 7.3 TRUCK INSTRUMENTATION LOCATIONS AND MEASUREMENT NUMBERS

FIGURE 7.4 TEST INSTRUMENTATION & CONTROL SYSTEM BLOCK DIAGRAM

Table 8.1 HANDLING EQUIPMENT

ITEM NO.	DESCRIPTION	MFG/MODEL NO.	QTY.
1	Facility Crane (20,000 lb. Cap.)		1
2 '	Facility Handling Slings and Harnesses	MMC	As Req'd
3	Hydraulic Jacks		2
4	Coal Conveyor System		1
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Table 8.2 TEST EQUIPMENT

	Table 8.2 TEST EQUIPMENT	· · · · · · · · · · · · · · · · · · ·	
ITEM NO.	DESCRIPTION	MFG./MODEL NO.	QTY.
1	Computer (Shaker Control & Data Analysis)	Time Data/1923 30V	1
2	Shaker Gain Control & Monitor Console	MMC	1
3	Servo Amplifier	MMC	1
4	Hydraulic Actuator	Moog	2
5	Hydraulic Power Supply		1
6	Actuator Support, Slide Plates & Truck Support Assemblies	MMC/LAB 1007302	1
7	Automatic Bypass Valve		1
8	Accelerometer	U-D/75 D 21	2
9	Accelerometer	Columbia/302-2	8
10	Accelerometer	Statham/A5a-2.0 5.0,10.0-350	8
11	Displacement Transducers	<u> </u>	19
12	Load Cell		6
13	Force Gage	MMC	2
14	Charge Amplifier	Kistler/505Mlll	10
15	Bridge Amplifier	Dana	31
16	Summing Amplifier		2
17	Tape Recorder (FM/FM)	Honeywell	1
18	Multiplexer		1
19	De-Mux		1
20	Cable (100 foot mini-noise)	Microdot	10
21	Equipment Interconnecting & Power Cables		As
22	Hydraulic Plumbing		Req'd
22	"Agragite rimming		As Req'd
**		TO CANADA	
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TABLE 8.3 TEST MEASUREMENT SUMMARY

MEAS.	TRANSDUCER LOCATION	PURPOSE OF MEASUREMENT	SENS. AXIS
NO.	LOCATION	PEASUREFIENT	AALO
AV1	Car Left Side, Fwd. End	To Meas. Car Vert. (Z) &	2
AV2	, Middle	Roll (TX) Acceleration	
AV3	, Aft End		
AV4	Car Right Side, Fwd. End		
AV5	, Middle		
AV6	, Aft End	< ♥	<b>∀</b>
AL1	, Fwd. End	To Meas. Car Lateral (Y)	Y
AL2	, Middle	Accelerations	1 1
AL3	, Aft End	•	
AL4	Axle, Opposite Wheel 1	To Meas., Axle, (X) & (TZ) Accel.	Х
AL5	i i	, (Y) Accel.	- <b>X</b>
AL6	Bolster, Left Side	To Meas., Bol., (X) & (TZ) Accel.	Х
AL7	<b>♦</b>	, (Y) Accel.	-Y
AL8	Axle, Opposite Wheel 2	To Meas. Axle, (X) & (TZ) Accel.	Х
AL9	<b>V</b>	, (Y) Accel.	-Y
AL10	Axle, Opposite Wheel 3	, (X) & (TZ) Accel.	X
AL11	Bolster, Right Side	To Meas. Bol., (X) & (TZ) Accel.	1 1
AL12	Axle, Opposite Wheel 4	To Meas. Axle, (X) & (TZ) Accel.	7
DV1	Btwn. Bol. & Side Frame L. Side	To Meas. Rel. Displ. (Z)&(TX) of	2
DV2	Rt. Side	Bolster WRT Side Frame	1
DV3	Btwn. Bol. & Car Left Side	To Meas. Rel. Displ. (Z) &	1 1
DV4	Rt. Side	(TX) of Bol. WRT Car	₹
DL1	Btwn. Bol. & Car Left Side	To Meas. Rel. Displ. (X) & (TZ)	X
DL2	Rt. Side • •	of Bol. WRT Car	<b>y</b>
DL3	▼ Center	To Meas. Rel. Displ. (Y) of Bol.	Y
1		WRT Car	
DL4	Btwn. S. Fr. & Axle, Wheel 1	To Meas. Rel. Displ. (Y) of	1 1
DL5	2	Side Frame WRT Axle	ļ 1
DL6	3,		
DL7	4	To Mong Pol Dioni (V) of	V ·
DL8	1 2	To Meas. Rel. Displ. (X) of Side Frame WRT Axle	î
DL10	4	orde Liquie MIT WITE	
DL10 DL11	3	•	
DL11	Btwn. Bol. & Side Fr. L. Side	To Meas. Rel. Displ. (X) & (TZ)	1
DL13	Rt. Side	of Bol. WRT Side Frame	\ ▼ .
DL13	L. Side	To Meas. Rel. Displ. (Y) of	Y
DL15	Rt. Side	Bol. WRT Side Frame	•
			<del>                                     </del>
FV1	Btwn. Actuator & Car L. Side	To Meas. Vert. (Z) Input Force	Z
FV2	Btwn. Wheel 1 & Facility Floor	To Meas. Vert. Force @ Wh. 1	J .
FV3	4 2	<b>★</b> *	♦
FV4	Been Actuator & Avia Onn Wh 1	To Meas. Lat. (Y) Input Force	<b>1 v</b>
FL1	Btwn. Actuator & Axle, Opp. Wh. 1	To Meas. Mac. (1) Input Porce	•
FL2	2		1 1
FL3	1 2		🍝
FL4	1 Y 3	Y Y	1 <b>y</b>

MEAS. NO.	XDUCR MODEL NO.	XDUCR SENS.	SIG. COND. CH. NO.	TAPE CH. NO.	TAPE FS CALIB.	XDUCR S/N	CABLE NO.				
AV1							·				
AV2											· · · · · · · · · · · · · · · · · · ·
AV3						,	<u>.</u>				,
AV4											-
AV5				,							
AV6											
AL1									<i>,</i>		-
AL2											
AL3		-									-
AL4			<u></u>								** .
AL5	,		<del> </del>		· · · · · · · · · · · · · · · · · · ·					<u> </u>	
AL6		-					,				
AL7		<del></del>	<b>-</b>			<u>`</u>					
AL8	· · · · · ·				-						
AL9											
AL10				· · · · · · · · · · · · · · · · · · ·							
AL11		L									
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MEAS.	XDUCR. MODEL NO.	XDUCR. SENS.	SIG. COND. CH. NO.	TAPE CH. NO.	TAPE FS CALIB.	XDUCR. S/N	CABLE NO.				
DV1							-				
DV2											
DV3		· · · · · · · ·									
DV4								· · · · · · · · · · · · · · · · · · ·			
DL1										<b> </b>	
DL2											
DL3		†		· · · · · ·		•		· · · · · ·			
DL4										· ·	
DL5				,			<del></del>				
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DL7											
DL8							-				
DL9					· · · · · · · · · · · · · · · · · · ·		·				
DL 10										,	
DL11											
DL12	,							· · · · · · · · · · · · · · · · · · ·			
DL13		<b></b>									
DL14										,	
DL15											
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MEAS. NO.	XDUCR. MODEL NO.	XDUCR. SENS.	SIG. COND. CH. NO.	TAPE CH. NO.	TAPE FS CALIB.	XDUCR. S/N	CABLE NO.				
FV1							1				
FV2			<del> </del>								
FV3	`		ļ		<u> </u>			<u> </u>	, ·		
FV4			<u> </u>								
rv4						<u> </u>		<u></u>			· · · · · · · · · · · · · · · · · · ·
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FL1									. •		
FL2		. •								<del></del>	-
FL3		,							<u> </u>		
FL4		<del></del>	<del> </del>		<del></del>	<del></del>				<u> </u>	
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Table 8.5 TEST HISTORICAL LOG

TIME	DATE	RUN NO.	TEST DESCRIPTION	REMARKS
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